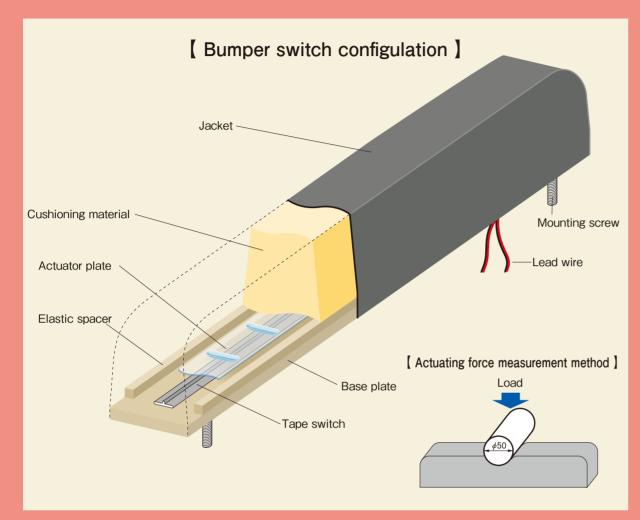
TOKYO SENSOR BUMPER SWITCH

Contact detection function and cushioning (impact absorption) performance



The sensor for detecting contact and collision, which also has excellent cushioning performance Flexibly meets a wide variety of needs concerning the incorporation of a wire breakage detection circuit, as well as such factors as sensitivity, size, and shape.



- * Contact and collision detection senso
- * Can be custom-made according to the desired size, shape, and operating load, etc.
- * Uses shock-absorbing material with excellent cushioning performance
- * Can detect a broken wire when combined with an FSC controller.

Basic specifications

Rated voltage	5 - 24 V AC/DC
Rated current	0.01 - 0.3 A (resistive load)
Insulating resistance	10 MΩ min (250 VDC)
Dielectric strength between electrodes	250 VDC for 1 minute
Operating temperature range	0 - 50°C

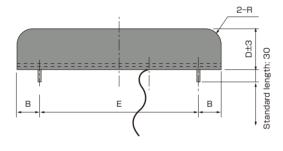
BUMPER SWITCH.

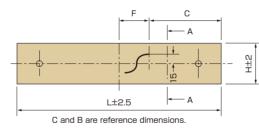
A bumper switch is a custom-made item, so be sure to provide details on the desired specifications using a drawing.



Specifications	Standard	Options			
Jacket	Synthetic leather	Synthetic leather	Splash	Lastan (heat resistant)	Aluminum leather
Jacket color	Black	Specified color	Black	Gray	Metallic luster
How the jacket is stitched together	Single layer with the ends stitched	Piping around the edges (in your specified color), stitching			
Shock absorbing material		Urethane foam			
Base plate	Plywood 12 mm thick	Steel plate, aluminum plate, stainless steel plate			
	Max length 2,400 mm				
Mounting screws	M8 ι=30mm	To be specified by the customer			
Actuating force	20 - 100 N (Differs according to size and application				
Wire type	VFF (vinyl flat cord)	4-wire type			
Lead wire	2-core 0.3 mm2 Red & black × 2	To be specified by the customer			
	500mm				
Length of lead wire		To be specified by the customer			
Option		Please consult us regarding clean room specifications and water resistance for your specific application needs.			

Reference drawing (It is necessary to specify the dimensions.)

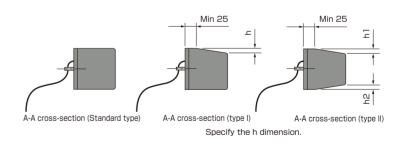


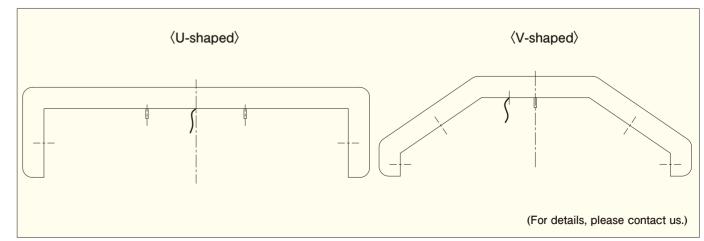


imensions and shape of sensor body. Ir	nsert the dime	nsions in [].Ite	ms marked * must be fi	lled in
L: Length	*[mm	
D: Depth	*[] mm		
H: Height	*[mm	
R: Corner radius (R≦D-25)	*2-R[
B: Mounting screw position	*[mm	
E: Pitch between mounting screws	*[)	mm	
O: When specifying mounting screws	[]-M[] Length [
C: Lead outlet position	*[] mm		
Δ: When specifying lead wire length	[] mm		

Specify the number of lead ou	tlet positions.	
Circle one.	* 1 location 2 locations	
When specifying 2 lead outlet positions	Pitch between lead wires [] mn
T	D. : E0	

The minimum value of the H dimension and the D dimension is 50 mm.





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